

Development of Backhoe Machine By 3-D Modelling using CAD Software and Verify the Structural Design By using Finite Element Method

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Abstract

Present study covers the detailed design, modelling and FE analysis of Backhoe Machine. . Backhoe Loader is the the rear part of the excavator machine. The backhoe loader is used for a wide variety of tasks: construction, small demolitions, light transportation of building materials, powering building equipment and digging holes/excavating, landscaping, breaking asphalt and paving roads. Various loads are applied at the bucket tip and to the boom and digger arm. So it is necessary to analyze the parts assembly to avoid failure while it is in working condition. From static analysis, high stress area can be found out when Backhoe Loader is in different load condition. Also by providing some design changes, stress can be minimized.

Keywords: Backhoe Loader; Stress Analysis; FEM

I. INTRODUCTION

Today in the machine age when the use of machines is increasing for the earth moving works, considerable attention has been focused on designing of these earth moving equipments. Achievement of an ambitious and rapidly growing rate of industry of earth moving machines is assured through the high performance construction machineries with complex mechanism and automation of construction activity. Bulldozers, scrapers, motor graders, excavators and other machines are widely used for most arduous earth moving work in engineering construction. Thus it is very much necessary for the designers to provide not only an equipment of maximum reliability but also of minimum weight and cost keeping design safe under all loading conditions by careful stress analysis of the machines.

II. STATIC FORCE ANALYSIS

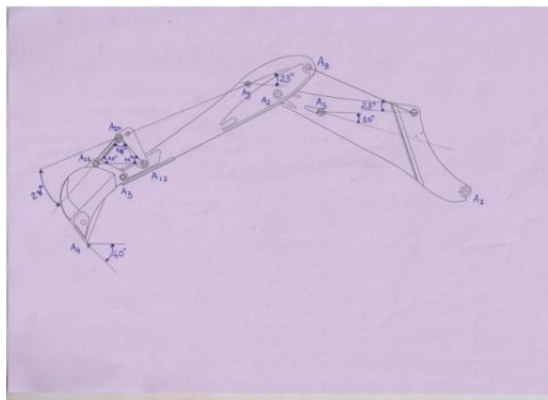


Fig. 1: Free Body Diagram of Backhoe Assembly

A. Bucket Static Force Analysis:

The reaction force on the bucket teeth at point A₄ due to breakout force 60100 N acts at the angle 40° for configuration of the breakout force condition. Reaction forces on point A₄ is resolved in horizontal (X) and vertical (Y) direction.

$$F_{4H} = F_B * \cos(\alpha_1) \\ = 46039.27 \text{ N}$$

Where α_1 is the angle between the breakout force of bucket and the ground level as horizontal reference surface of 40°

$$F_{4V} = F_B \cdot \sin(\alpha_1) \\ = 38631.53 \text{ N}$$

Now considering the bucket in equilibrium $\Sigma M = 0$, taking moment about the bucket hinge point A_3 leads to

$$F_4 \cdot l_4 - F_{gb} \cdot l_{gb} = F_{11} \cdot l_{11} \\ \therefore F_{11} = 182032.46 \text{ N} \\ F_{11H} = F_{11} \cdot \cos \beta_{11} \\ = 121803.49 \text{ N} \\ F_{11V} = F_{11} \cdot \sin \beta_{11} \\ = 135276.48 \text{ N}$$

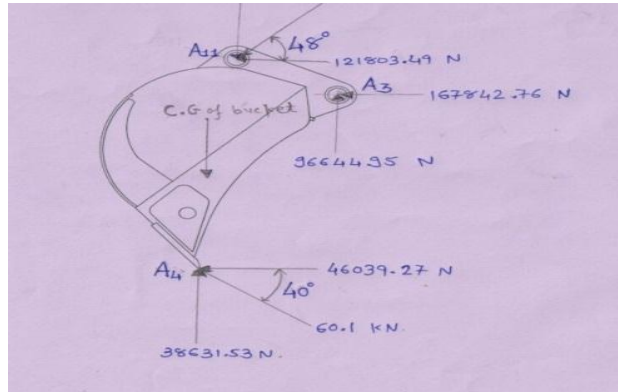


Fig. 2: Free Body Diagram of Bucket

Table - 1
Forces on Bucket

Joint of the bucket	Forces (N) Horizontal (X) component	Forces (N) Vertical (Y) component
A_4	-46039.27	38634.53
A_{11}	-121803.49	-135276.48
A_3	167842.76	96644.95

The negative sign shows the force acting in the leftward direction for horizontal component of the force and downward direction for vertical component of the force.

B. Arm Static Force Analysis:

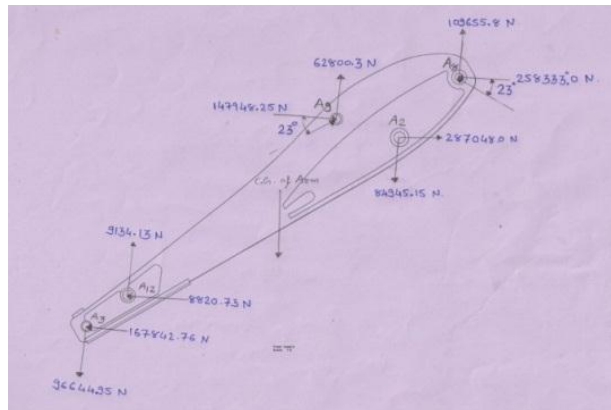


Fig. 3: Free Body Diagram Of Arm

The Force (F_{12}) is the force acting on the intermediate link ($A_{10}A_{12}$) from the idler link ($A_{11}A_{10}$) at an angle β_{10} of 86°

$$F_{12} = F_{11} \cdot \cos \beta_{10} \\ = 12697.94 \text{ N}$$

$$F_{12H} = F_{12} \cdot \cos \beta_{12} \\ = 8820.73 \text{ N}$$

$$F_{12V} = F_{12} \cdot \sin \beta_{12} \\ = 9134.13 \text{ N}$$

The force F_9 is acting on arm through the bucket cylinder, at an angle β_{10a} of 28°

$$F_9 = F_{11} \cdot \cos \beta_{10a} \\ = 160725.12 \text{ N}$$

The force F_9 can be resolved in horizontal (X) and the vertical (Y) directions. Here, β_9 is the angle made by force on arm through bucket cylinder with horizontal reference of 23°

$$F_{9H} = F_9 \cdot \cos \beta_9$$

$$= 147948.25 \text{ N}$$

$$F_{9V} = F_9 \cdot \sin \beta_9$$

$$= 62800.3 \text{ N}$$

Considering the arm in equilibrium $\Sigma M = 0$ and taking moment about the arm to boom hinge point (A_2) leads to;

$$F_8 \cdot l_8 = -(F_{3V} \cdot l_{3H}) - (F_{ga} \cdot l_{ga}) + (F_{3H} \cdot l_{3V}) + (F_{12} \cdot l_{12}) + (F_9 \cdot l_9)$$

$$F_8 = 280642.76 \text{ N}$$

$$F_{8H} = F_8 \cdot \cos \beta_8$$

$$= 258333.027 \text{ N}$$

$$F_{8V} = F_8 \cdot \sin \beta_8$$

$$= 109655.8 \text{ N}$$

Table - 2
Point Forces on Arm

Joint of the bucket	Forces (N) Horizontal (X) component	Forces (N) Vertical (Y) component
A_3	-167842.76	-96644.95
A_{12}	-8820.73	9134.13
A_9	147948.25	62800.3
A_8	-258333.0	109655.8
A_2	-287048.0	84945.15

C. Boom Static Force Analysis:

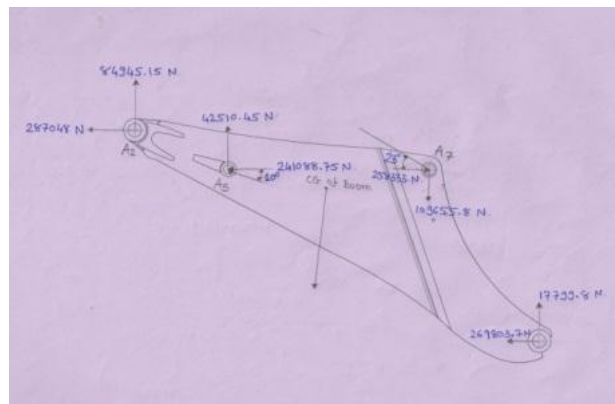


Fig. 4: Free Body Diagram of Boom

force F_7 is the force acts by arm at point A_7 through arm cylinder which is same as the force F_8 but direction is opposite. The force F_7 can be resolved in horizontal (X) and the vertical (Y) directions Here, β_7 is the angle made by force on boom through arm cylinder with horizontal reference at point A_7 of 23°

$$F_{7H} = 258333.027 \text{ N}$$

$$F_{7V} = 109655.8 \text{ N}$$

Considering the boom in equilibrium $\Sigma M = 0$ and taking moment about the arm to boom hinge point (A_1) leads to;

$$(F_5 \cdot l_5) = -(F_{2H} \cdot l_{2V}) - (F_{gbo} \cdot l_{gbo}) + (F_{2V} \cdot l_{2H}) + (F_7 \cdot l_7)$$

$$F_5 = 244807.94 \text{ N}$$

$$F_{5H} = F_5 \cdot \cos \beta_5$$

$$= 241088.75 \text{ N}$$

$$F_{5V} = F_5 \cdot \sin \beta_5$$

$$= 42510.45 \text{ N}$$

The forces on each of the joints of the boom are shown in table 7.3.

Table - 3
Point Forces on Boom

Joint of the bucket	Forces (N) Horizontal (X) component	Forces (N) Vertical (Y) component
A_2	-287048.0	84945.15
A_7	258333.02	-109655.8

A_5	-241088.75	42510.45
A_I	269803.7	17799.8

III. DESIGN CALCULATIONS

1) Old Material:

Pin: Carbon steel EN 9 grade

2) New Material:

Tooth and tooth plate of bucket: Hardox 400

Pin: Carbon steel EN 9 grade

Remaining parts: SAILMA 450 HI

A. Design Calculations of Pins Bucket Pin Design:

The bucket pin is checked for bearing, shear and bending failure.

- Diameter of bucket pin, $d_b=60$ mm
- Total length of the bucket pin, $l_{pb}=300$ mm
- Effective length of the bucket pin, $l_{pbe}=190$ mm

Let us first check the bucket pin for bearing failure. For the calculation, the effective length of the bucket pin (the portion of bucket pin which is in contact with the arm) is considered.

- The resultant force acting on the bucket pin is,

$$F_{pb}=F_3= \sqrt{F_3H^2 + F_3V^2} \quad F_3= 186656 \text{ N}$$

- Also, the bearing force acting on the bucket pin is,

$$F_{pb}=d_b \cdot l_{pbe} \cdot p_b$$

$$p_b= 186656 / (60 \cdot 190)$$

$$=16.37 \text{ Mpa}$$

Here, the bearing pressure induced in the bucket pint is very less compared to the allowable bearing pressure of bucket pin material carbon steel EN 9 as 130 MPa. So, the bucket pin is safe in bearing

- Considering bucket pin is in double shear and the shear area of the bucket pin is, $A_{pb}=2 \cdot \pi/4 \cdot (d_b)^2$

Now, shear force acting on the bucket pin is,

$$F_{pbfs}=2 \cdot (\pi/4) \cdot (d_b)^2 \cdot \tau_{shear} \quad \tau_{shear}= (2 \cdot 186656) / (\pi \cdot 60^2)$$

$$= 33.009 \text{ Mpa}$$

Here, the shear stresses developed in the bucket pin is very less compared to allowable shear stress of bucket pin material steel EN 9 as 160 MPa. So, the bucket pin is safe in shear.

Consider bucket pin as simply supported beam with uniformly distributed loading condition as shown in Fig. 5.1 and now let us check bucket pin for bending failure.

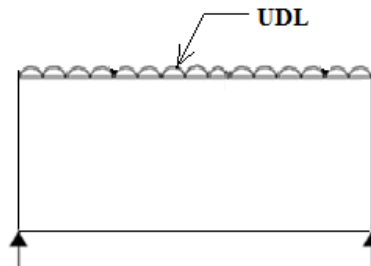


Fig. 5: Pin with UDL Condition

$$\begin{aligned} \sigma_{max} &= (M_b \cdot Y_{max}) / I_b \\ &= (4 \cdot F_b \cdot L) / (\pi \cdot d^3) \\ &= 209.057 \text{ Mpa} \end{aligned}$$

The maximum bending stress developed in the bucket pin is within the stress limit of the bucket pin material, therefore the design of bucket pin is safe in bending.

By using the above equations for all pins, obtained results are plotted in below table.

Table - 4
Pin Calculations

Pin	Axial force N	Old pin dia. Mm	New pin dia. Mm	Total length mm	Effective length mm	Maximum Bearing pressure, Mpa	Maximum shear stress Mpa	Maximum bending stress Mpa
A1	270390	70	70	449	265	14.57	35.13	265.99
A7	280642	55	55	318	120	42.52	59.06	257.7
A10	182032	45	50	252	102	35.69	46.35	184.13
A11	182032	55	60	326	190	15.96	32.19	203.87
A12	12697	40	40	316	200	1.58	5.05	50.52
A3	186656	55	60	300	190	16.37	33.09	209.57
A8	280642	60	65	296	176	24.53	42.28	229.06
A5	244807	60	60	306	170	24.00	43.29	245.32
A2	299353	65	65	262	177	26.01	45.10	245.66
A9	160725	50	55	306	170	17.18	33.82	209.10

Above table shows the calculation for all pin which shows that all pins are more safe. By comparing the above results with the materials properties it is found that maximum bearing pressure, maximum shear stress and maximum bending stress is within the limit of allowable stresses.

B. Analysis of Backhoe Assembly:

1) Scope of Analysis

The Analysis report presented herewith deals with the Finite Element Analysis of the backhoe. It presents the structural analysis of the backhoe assembly.

IV. GEOMETRY

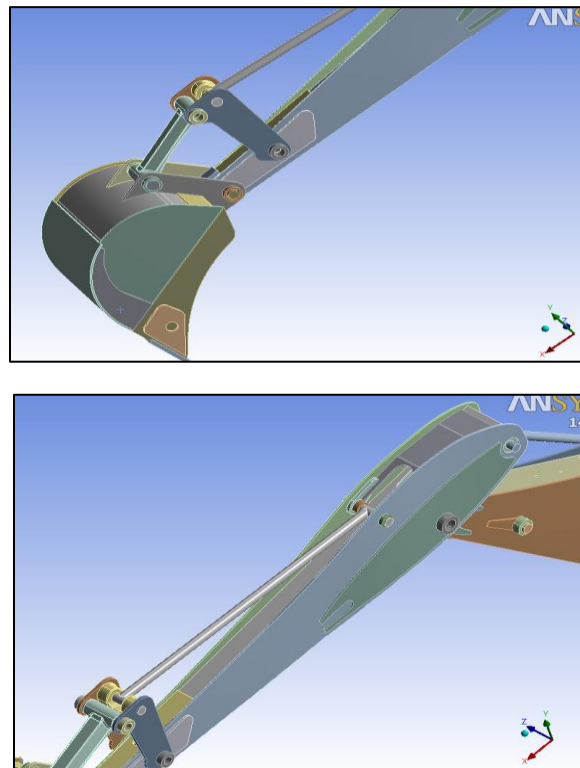


Fig. 6: Views of Backhoe Assembly

A. Load Case:

Structural Analysis has been performed by applying the breakout force at the teeth of bucket.

1) FEA Details – Mesh Details:

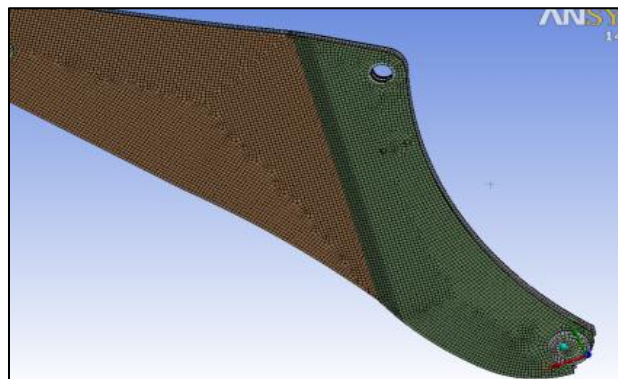
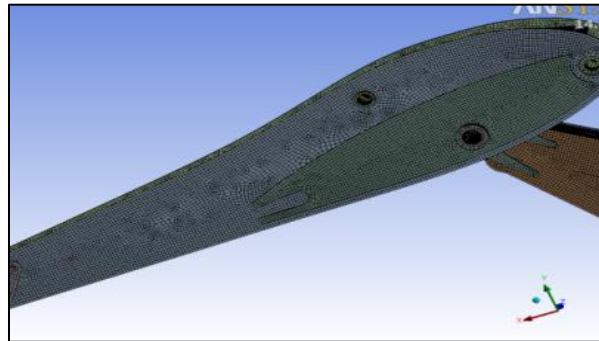
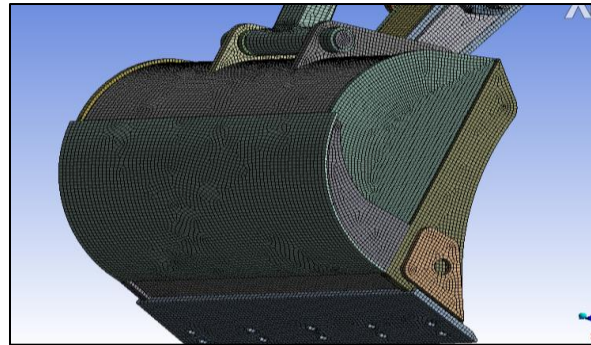
Table – 5
FE Model Summary

Description	Quantity
Total Nodes	1136758
Total Elements	269741

Table – 6
Elements Type Summary

Generic Element Type Name	Ansys Name	Description
10 Node Quadratic Tetrahedron	Solid187	10 Node Tetrahedral Structural Solid
20 Node Quadratic Hexahedron	Solid186	20 Node Structural Solid
20 Node Quadratic Wedge	Solid186	20 Node Structural Solid
20 Node Quadratic Pyramid	Solid186	20 Node Structural Solid

V. MESHING OF ASSEMBLY



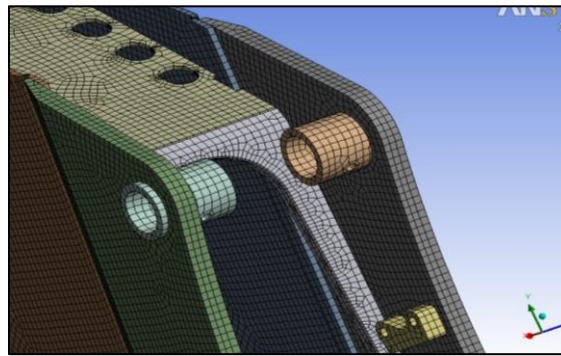


Fig. 7: Meshing of Assembly

– Constraints

Following Constraints are applied in order to simulate the actual Joint for FEA:

A. Bonded Contact Between Each Part To Simulate Welded Joint:

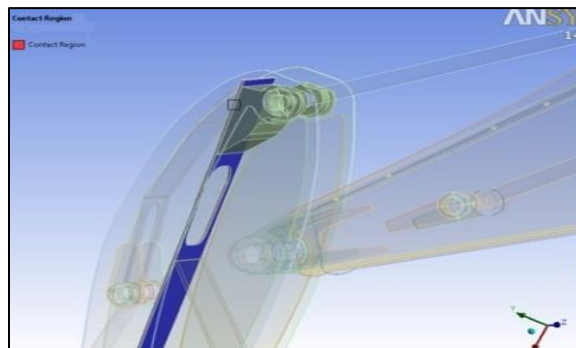
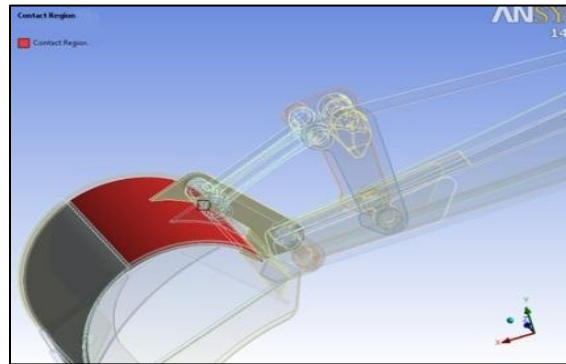
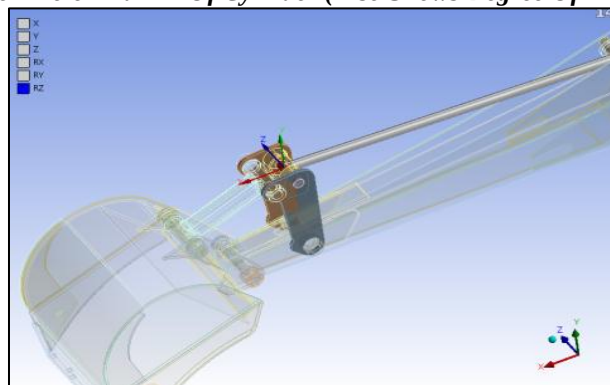


Fig. 8: Applied Constraints 1

B. Rigid Link Connection Between Hole And Pin Of Cylinder (Also Shows Degree Of Freedom Of Part):



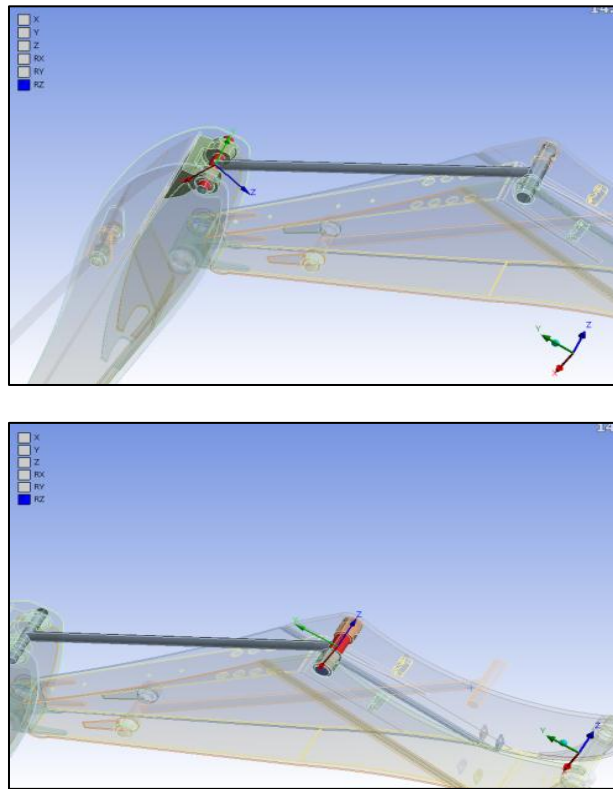


Fig. 9: Applied Constraints 2

Here each pin constrained to rotate about Z axis only. Also cylinders are considered as a rigid link, so rotation about X and Y are zero, so each element is allowed to rotate in XY plane with respect to Z axis.

1) *Loads:*

Load Case : Structural analysis by applying breakout force at the teeth location

2) *Fix support Self Weight:*

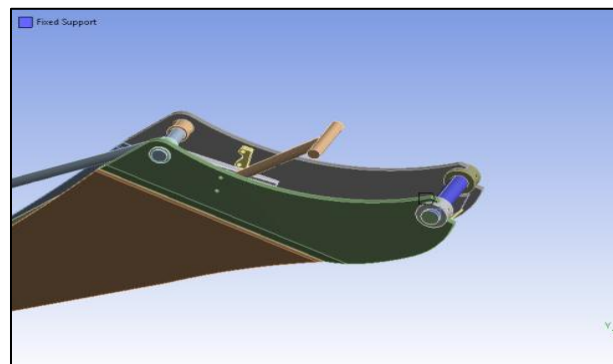


Fig. 10: Fixed Support

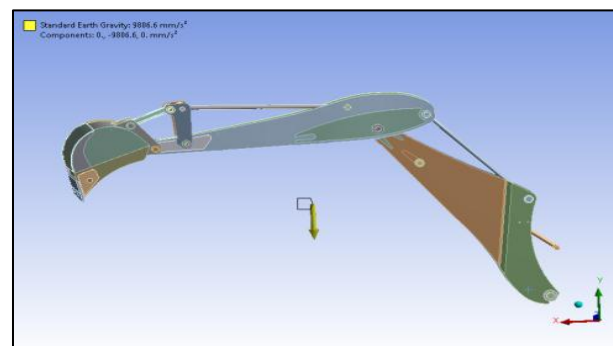


Fig. 11: Self-Weight

3) Breakout Force:

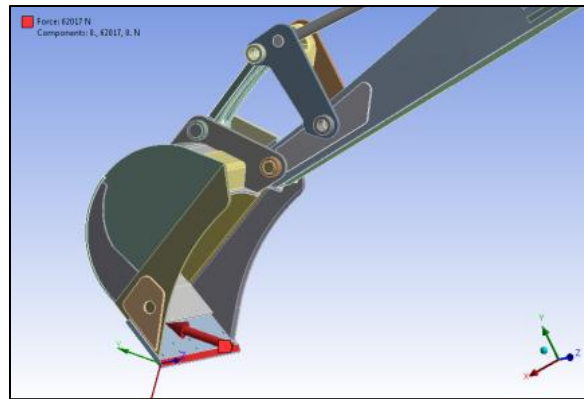


Fig. 12: Applied Breakout Force

C. Results:

Load Case - Total Deformation

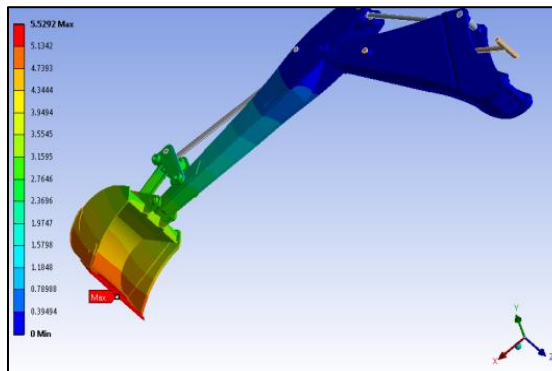
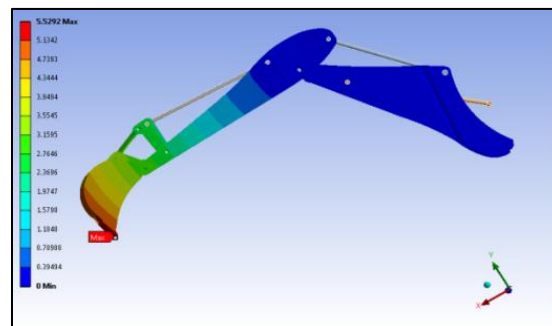
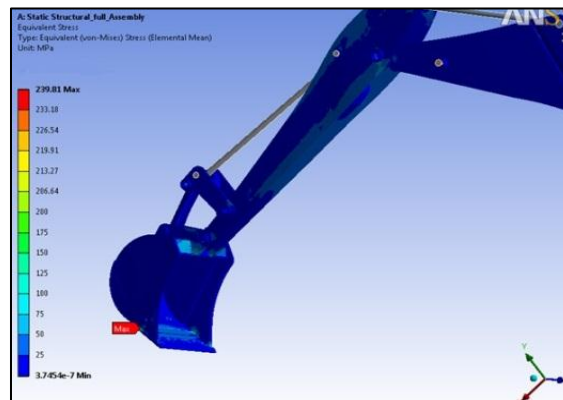


Fig. 13: Total Deformation

D. Equivalent Stress:



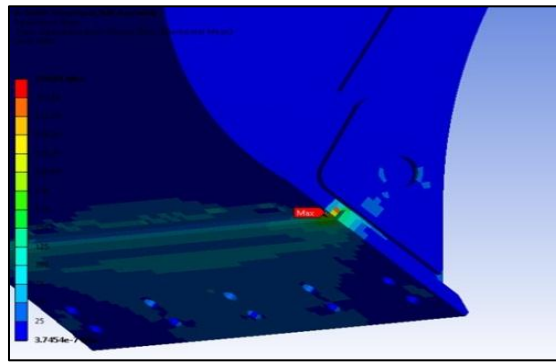


Fig. 14: Equivalent Stress (Von Mises Stress)

VI. RESULTS

- 1) Stresses are well within the allowable stress for the entire area. There is a stress concentration at the point where the max force is applied, which can be neglected.
- 2) The total deformation at the bucket teeth point is 5.5292 mm which is negligible.
- 3) By increasing pin diameter at critical loading points strength of the assembly is increased.
- 4) Variation in pin diameter is shown in table
- 5) By changing the material of the components of backhoe and by trial and error method in ANSYS following results are obtained

Table - 7

Component	Modifications		Total weight (Kg)		% Reduction
	Thickness before modification mm	Thickness after modification mm	Weight before optimization	Weight of optimized model	
Bucket	No change in bucket thickness so as to strengthen it more.		240	240	0%
Dipper	12 mm side plates.	10 mm	337	285	52 kg 15%
	8 mm top and bottom covers.	7 mm			
Boom	25 mm side plates at pivot joint	24 mm	380	340	40 kg 11 %
	12 mm side plate	10 mm			
	8 mm top and bottom covers	7 mm			

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